

**THE KAVERY ENGINEERING COLLEGE**  
(An Autonomous Institution)

M.E DEGREE END SEMESTER THEORY EXAMINATIONS, NOV /DEC 2024

*Second Semester*

*Power Systems Engineering*

PS4202 - Power System Dynamics

*Regulations - 2021*

*Duration : 3 Hrs*

*Maximum : 100 Marks*

**PART - A (ANSWER ALL QUESTIONS) (Marks 10\*2=20)**

| <i>Q.No</i> | <i>Questions</i>                                                                             | <i>BLT</i> | <i>CO</i> | <i>Marks</i> |
|-------------|----------------------------------------------------------------------------------------------|------------|-----------|--------------|
| 1.          | List the components of the armature and field structure in a synchronous machine.            | RE         | 1         | 2            |
| 2.          | Recall the significance of the direct and quadrature axes in synchronous machine modeling.   | UN         | 1         | 2            |
| 3.          | Write the function of an excitation system in synchronous machines.                          | RE         | 2         | 2            |
| 4.          | Illustrate the classical transfer function of a hydraulic turbine.                           | UN         | 2         | 2            |
| 5.          | What is the importance of eigenvalues in the stability of dynamic systems?                   | RE         | 3         | 2            |
| 6.          | Interpret the effect of field flux variation on system stability.                            | UN         | 3         | 2            |
| 7.          | Name the main components of a thyristor excitation system with AVR.                          | RE         | 4         | 2            |
| 8.          | Compare the roles of the AVR and the Power System Stabilizer (PSS) in stability enhancement. | UN         | 4         | 2            |
| 9.          | Recall the purpose of a digital stabilizer.                                                  | RE         | 5         | 2            |
| 10.         | Summarize the design elements required for effective excitation control.                     | UN         | 5         | 2            |

**PART - B (ANSWER ALL QUESTIONS) (Marks 5\*13 = 65)**

| <i>Q.No</i> | <i>Questions</i>                                                                                                                                                                                                                                                                                | <i>BLT</i> | <i>CO</i> | <i>Marks</i> |
|-------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------|-----------|--------------|
| 11.         | a Explain the dq0 transformation and its physical interpretation in synchronous machine modeling.<br>Or<br>b Demonstrate the computation of steady-state values in a synchronous machine using phasor relationships.                                                                            | AP         | 1         | 13           |
| 12.         | a Interpret the modeling process for IEEE type ST1A (1992) excitation model components.<br>Or<br>b Explain the purpose and block diagram of a governor with transient droop compensation for a hydraulic turbine.                                                                               | AP         | 2         | 13           |
| 13.         | a Apply state-space representation and eigenvalue analysis to assess the stability of a dynamic system. Explain it with an example.<br>Or<br>b Solve a stability analysis for a Single-Machine Infinite Bus (SMIB) configuration with a classical machine model, including a numerical example. | AP         | 3         | 13           |

14. a Construct the system state matrix for a two-machine system with synchronous machines modeled classically. AP 4 13
- Or
- b Develop a block diagram for a power system with AVR and PSS, discussing how they affect synchronizing and damping torque. AP 4 13
15. a Model a stabilizer based on the shaft speed signal ( $\Delta\omega$ ) and explain its role in stability enhancement. AP 5 13
- Or
- b Utilize phase lead compensation in the design of excitation control for enhanced stability, including washout and stabilizer gain. AP 5 13

PART – C (Marks 1\*15 = 15)

| <i>Q.No</i> |     | Questions                                                                                                                    | <i>BLT</i> | <i>CO</i> | <i>Marks</i> |
|-------------|-----|------------------------------------------------------------------------------------------------------------------------------|------------|-----------|--------------|
| 16.         | a   | Obtain the mathematical model of,<br>i. Single reheat tandem compounded type steam turbine (8)<br>ii. Hydraulic turbine (7)  | AP         | 2         | 15           |
|             |     | Or                                                                                                                           |            |           |              |
|             | b i | Plan the application of a Power System Stabilizer in a multi-machine system, illustrating with a two-machine system example. | AP         | 4         | 7            |
|             | ii  | Explain the stabilizer limits and selection of PSS location.                                                                 | AP         | 5         | 8            |